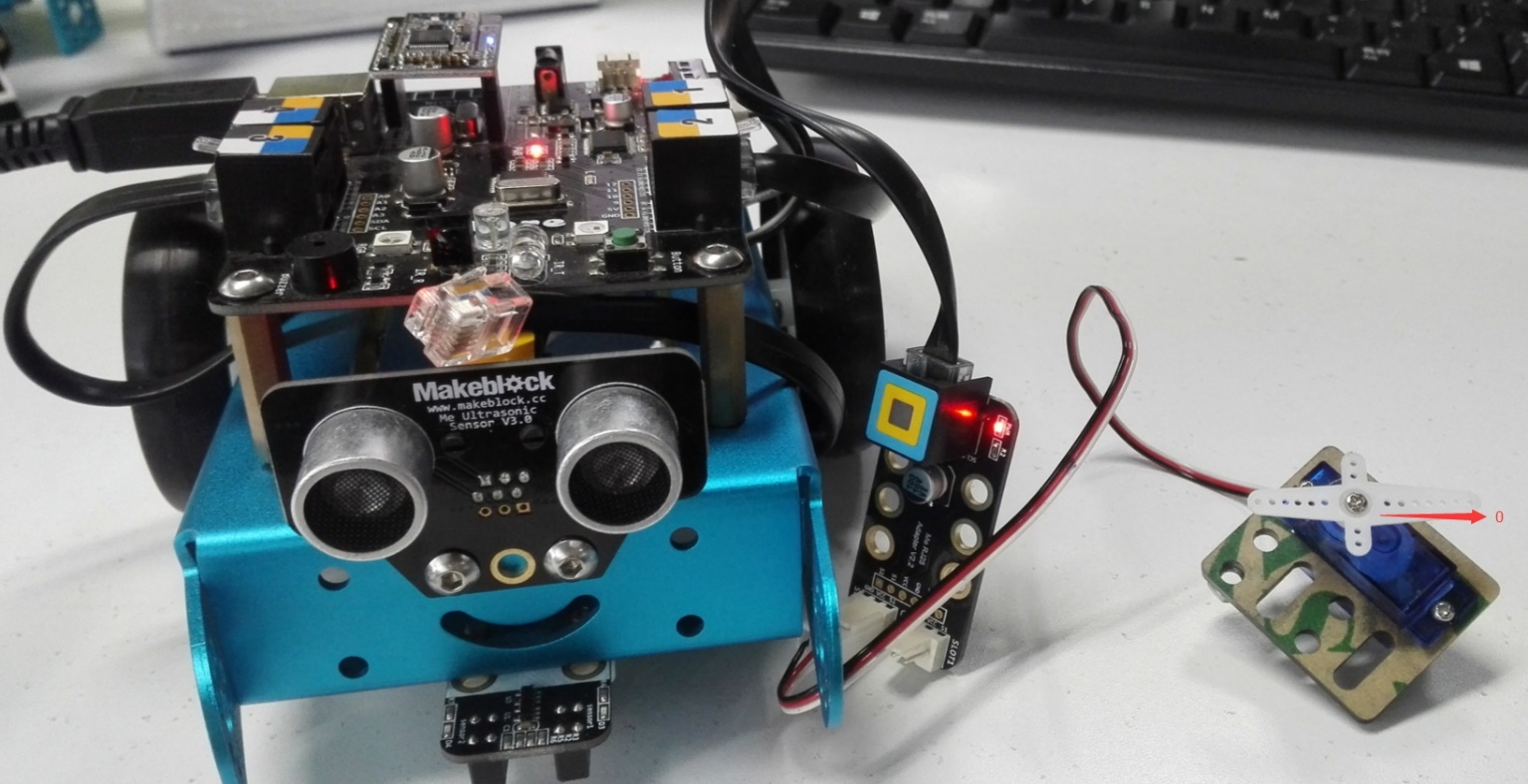
Please see bellow examples to test the function of the servo (here I connect RJ25 adapter to Port 2 on mCore and connect servo to Slot 2 on RJ25 adapter  ):

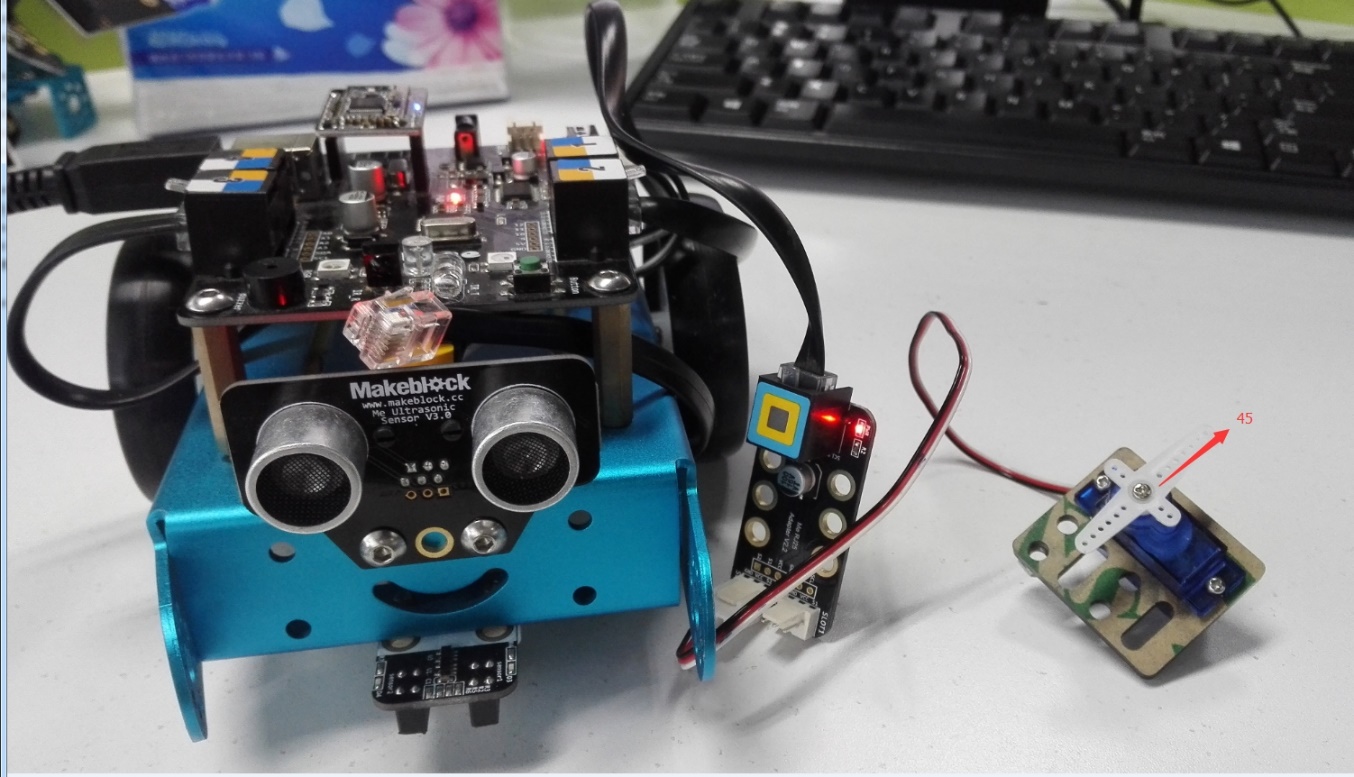
1. Control the servo to 0 degrees





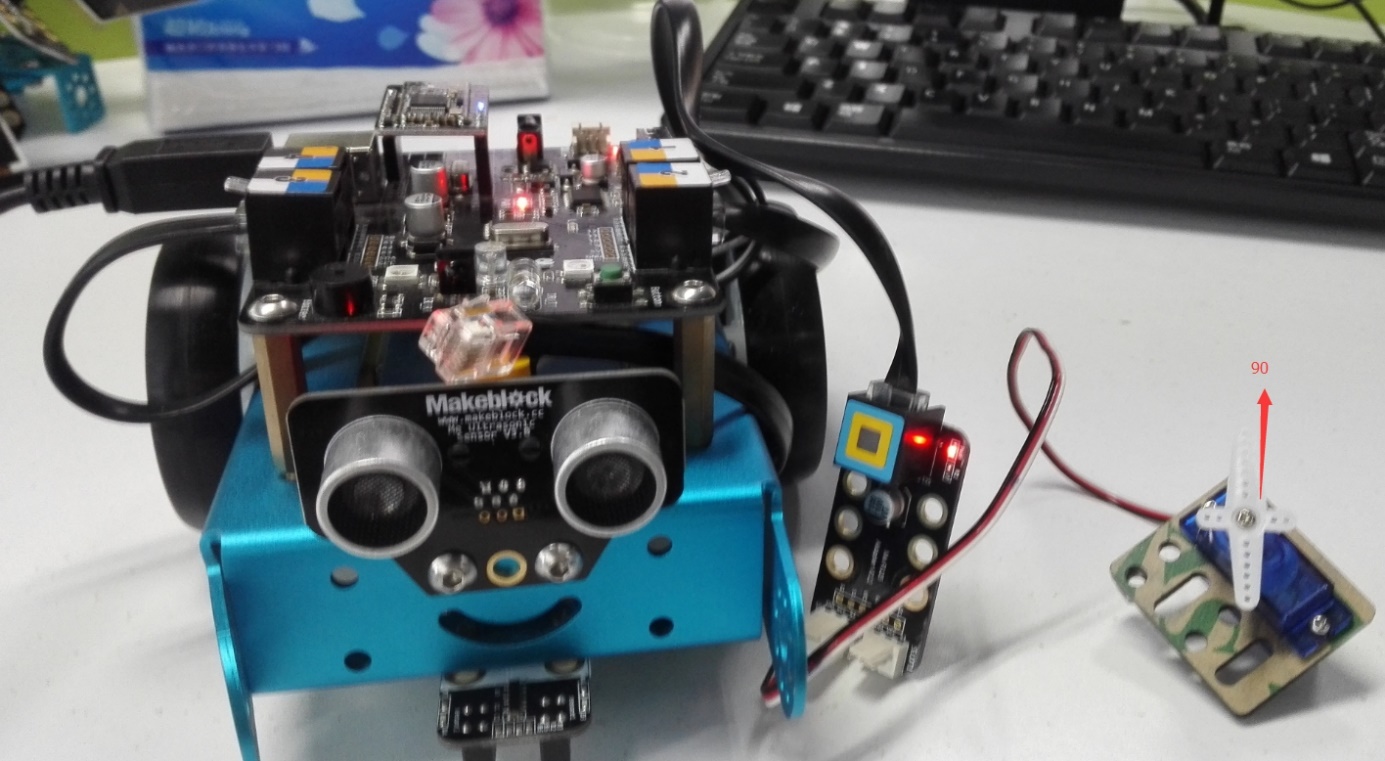
2. Control the servo to 45 degrees





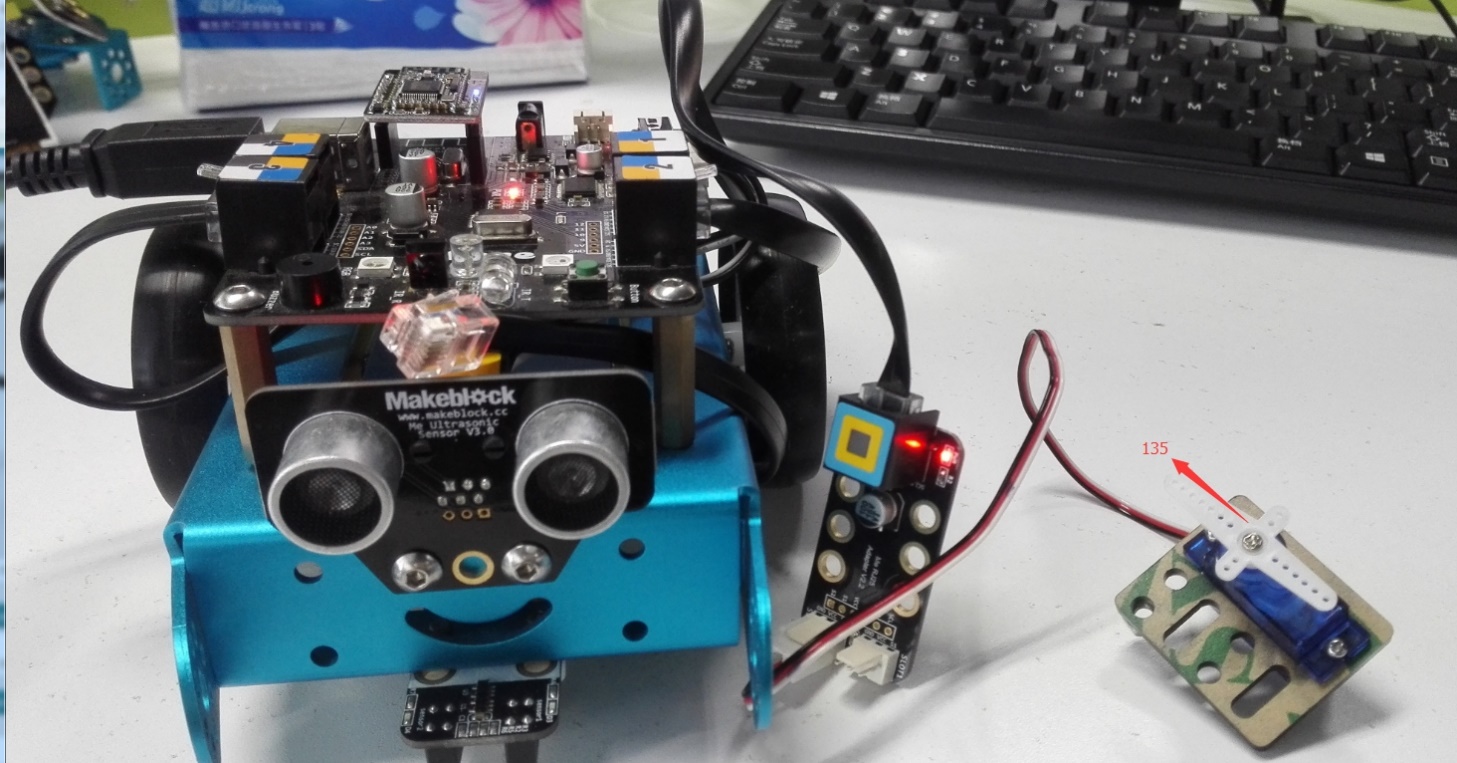
3. Control the servo to 90 degrees

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4. control the servo to 135 degrees

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5. control the servo to 180 degrees

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